**Command list**

Note:

~ denotes commands containing information or warnings

/ denotes commands that will be executed

|  |  |  |
| --- | --- | --- |
| Command | Command type | Description |
| 0 | Movement | Stop |
| 1 | Movement | Start |
| 2 | Debug | Read IR sensor state |
| 3 | Debug | Read distance using ultrasonic sensor |
| 4 | Debug |  |
|  |  |  |
|  |  |  |
| 5XX | Information | Obstacle detected at distance XX |
|  |  |  |
|  |  |  |